**SRI SIDDHARTHA ACADEMY OF HIGHER EDUCATION**

**(*Declared as Deemed to be University Under Section 3 of the UGC Act, 1956***

***Approved by AICTE, Accredited by NBA, NAAC ‘A’ Grade*)**

**AGALKOTE, TUMAKURU – 572107**

**KARNATAKA**



**Project Report**

**On**

**“Gesture Controlled Robot Using Sixth Sense Technology”**

Submitted by

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In partial fulfillment of requirements for the award of degree in

**BACHELOR OF ENGINEERING**

**IN**

**ELECTRONICS AND COMMUNICATION ENGINEERING**

Under the guidance of

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**SRI SIDDHARTHA INSTITUTE OF TECHNOLOGY**

**(A Constituent College of SRI SIDDHARTHA ACADEMY OF HIGHER EDUCATION, Approved by AICTE, Accredited by NBA, NAAC ‘A’ Grade)**

MARALUR, TUMAKURU-572105

**2018-2019**

**ACKNOWLEDGEMENT**

The satisfaction and euphoria that accompany the successful completion of any task would be incomplete without mentioning the people who made it possible and support had been a constant source of encouragement which crowned our efforts with success.

We are deeply indebted and we would like to express our sincere thanks to our beloved Principal **Dr. M.K.VEERAIAH,** for providing us an opportunity to do this project.

Our special gratitude to **Dr. M.Z.KURIAN,** HOD, Department of ECE, SSIT for his guidance, constant encouragement and wholehearted support.

Our sincere thanks to our guide **Mrs. MANJULA.Y** Asst. Prof, Department of ECE, SSIT for her guidance, constant encouragement and wholehearted support.

Finally we would like to express our sincere thanks to all the staff members of ECE department, SSIT for their valuable guidance and support.

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**DECLARATION**

We, **HARSHITHA GL**, **HEMAVATHI B**, **NITISH KUMAR** and **SAQIB MEHMOOD BHAT** hereby declare that, this project work entitled “**GESTURE CONTROLLED ROBOT USING SIXTH SENSE TECHNOLOGY**” is an original and bonafide work carried out by us at SSIT Tumakuru, in partial fulfilment of **BACHELOR OF ENGINEERING** in **Electronics and Communication Engineering**.

We also declare that, to the best of our knowledge and belief, the work reported herein does not form part of any other thesis or dissertation on the basis of which a degree or award was conferred on an earlier occasion by any student.

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**ABSTRACT**

Sixth sense is an approach to execute our ordinary and extraordinary efforts seemingly independent of the five senses. It is a wearable gestural interface, which provides freedom to interact with the digital world using hand gestures. The gestural interface device works on the principles of gestural recognition and image processing.

Gesture recognition is an approach that permits movement of hands as input controls. With the availability of many such smart devices which captures our special moments every time, considering the need of taking it out from pocket every time, our main centre of interest is to keep hands free by capturing images using a webcam and store them by using recognition method in MATLAB which acts as a processing interface for this technology.

Sixth Sense Technology is also used for the human electronic interaction using natural hand gestures. The hand gestures can be used to control any micro controller based devices or robots at distant places using ZigBee or GSM Module. The “Sixth Sense Technology” is easy to implement with reduced implementation cost and it opens a wide area of research for the next generation and a greater development in almost all areas of current interest. Sense Technology and its advancements can control the autonomous robots or any microcontroller based devices on human will. Currently autonomous robots or any microcontroller based devices are designed for a single purpose, but with this technology robots and those devices can be made to achieve multidimensional purposes. Even the costlier sensors can be replaced with the low cost night vision cameras. It opens a way to control robots or any microcontroller based devices at any distance with natural hand gestures of human beings. It also has the provision of customizable virtual keyboard for giving more actions to distant devices. It is going to be a greater field of research that also paves a lot of attention in this current world of technology.

**Keywords:** Colour recognition, gesture recognition, image processing, robotics, MATLAB, Sixth Sense Technology.

**CONTENTS**

|  |  |
| --- | --- |
| **CHAPTER** | **PAGE NO.** |
| 1. INTRODUCTION | 1 |
| * 1. Objective | 1 |
| * 1. Motivation | 2 |
| * 1. Problem Domain | 2 |
| * 1. Solution to the Problem | 2 |
| * 1. Methodology | 3 |
| 1. LITERATURE SURVEY | 4 |
| 1. SYSTEM DESIGN | 8 |
| 1. SYSTEM HARDWARE DESCRIPTION | 10 |
| * 1. PIC18F45K22 Microcontroller | 10 |
| * + 1. I/O Ports | 11 |
| * + 1. Internal Calibrated Oscillator | 11 |
| * + 1. Analog Features | 11 |
| 4.1.4 Timers/Counters | 11 |
| 4.1.5 Interrupts | 12 |
| 4.1.6 USART | 12 |
| 4.1.7 General Purpose Registers | 12 |
| 4.1.8 Memory | 12 |
| * 1. Motor Driver: L293D | 13 |
| * 1. DC Motor | 14 |
| * 1. Zigbee Module | 15 |
| * 1. Camera | 16 |
| * 1. Laptop or Personal computer | 16 |
| * 1. Coloured Markers | 17 |
| 1. SYSTEM SOFTWARE DESCRIPTION | 18 |
| 5.1. MATLAB | 18 |
| 5.2. mikroC PRO | 19 |
| 1. SYSTEM IMPLEMENTATION | 20 |
| 6.1. Acquiring Image | 21 |
| 6.2. RGB to Gray scale Conversion | 21 |
| 6.3. Extraction of Colour | 22 |
| 6.4. Gray to Binary scale Conversion | 22 |
| 6.5. Finding Centroid of an Image | 23 |
| 6.6. Serial Communication between MATLAB and Microcontroller | 23 |
| 1. RESULTS | 24 |
| * 1. Snapshot | 24 |
| * 1. Algorithm to get the Results | 25 |
| * 1. Object Extraction Results | 26 |
| * 1. Command Detection | 27 |
| 1. APPLICATIONS | 28 |
| 1. ADVANTAGES AND DISADVANTAGES | 29 |
| 9.1 Advantages | 29 |
| 9.2 Disadvantages | 29 |
| 10 CONCLUSION | 30 |
| 11 FUTURE ENHANCEMENTS | 31 |
| 12 REFERENCES | 32 |

**LIST OF FIGURES**

|  |  |  |
| --- | --- | --- |
| **FIGURE NO.** | **FIGURE TITLE** | **PAGE NO.** |
| 1.1 | Work flow Methodology | 3 |
| 3.1 | Functional Modelling Analysis of Entire System | 8 |
| 4.1 | PIC18F45K22 Development board | 10 |
| 4.2 | Motor Driver L293D | 13 |
| 4.3 | DC Motor | 14 |
| 4.4 | Zigbee Module | 15 |
| 4.5 | Camera | 16 |
| 4.6 | Laptop | 16 |
| 4.7 | Coloured Markers | 17 |
| 6.1 | Control flow block diagram | 19 |
| 7.1 | Snapshot of working model | 23 |
| 7.2.1 | Acquired Image | 25 |
| 7.2.2 | RGB to Grayscale Image | 25 |
| 7.2.3 | Colour Extraction | 25 |
| 7.2.4 | Required Binary Image | 26 |
|  |  |  |

**LIST OF TABLES**

|  |  |  |
| --- | --- | --- |
| **TABLE NO.** | **TABLE TITLE** | **PAGE NO.** |
| 7.1 | Object-Direction relationship | 26 |
|  |  |  |